

Nikos Mavrakis

UNIVERSITY OF
BIRMINGHAM



Background:

- B.Eng. And M.Eng. in Electrical and Computer Engineering
National Technical University of Athens
- M.Sc. in Space Studies
KU Leuven
- PhD candidate in Robot Grasping and Manipulation,
Extreme Robotics Lab, University of Birmingham

Research Interests:

- Estimation of objects' inertial parameters with robot vision and interaction
- Uses of inertial parameters in robot grasp and manipulation planning
- Applications in Extreme Environment Robotics (H2020 RoMaNS project)

Other Interests:

- Robot Building
- Vintage sci-fi books
- Travelling

