Alexis BILLIER

Early Stage researcher
Danieli TelerobotLabs, Genova

Curent Project : SECURE Project; Creation of guideline and development of a system that will allow robots to utilize social cues that significantly improve safe human-robot interaction in home environments

Nationality:
French

Date of birth:
11/05/1993

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Alexis Billier

DANIELI TELEROBOT LABS

Education

2015: M.Eng in Mecatronics Supmeca/ENSEA

Project

2015:UEC, Ming Laboratory, Chōfu (Japan)
Engineer internship (6 months): Behavorial Simulation using Matlab Simulink and Adams. Working on the Neco robot, to increase the jumping height of a biomimetic cat robot .